

The road from pilots to implementation. *Lessons learned based on knowledge gained from practice*



Workpackage 7: Casestudies & demonstrators

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When do you think we'll have AVs operating in our PT system?

- A. <5 years
- B. 5 – 10 years
- C. >10 years
- D. Never



From Appelscha to Japan

2016 – 2020

- **Appelscha**
- **Rotterdam the Hague Airport**
(collab. with Rebel Group)
- **WEpod**
- **Rivium ParkShuttle**
- **AV in Japan**
- **AV meets PT**
(collab. with Goudappel)
- **Automated buses in Europe**
(collab. with Autobus project)
- **TRB paper from pilot to implementation**



Final paper: TRB

Status: under review

What are the characteristics of promising situations where automated vehicles can be deployed in public transport based on knowledge gained from practice?



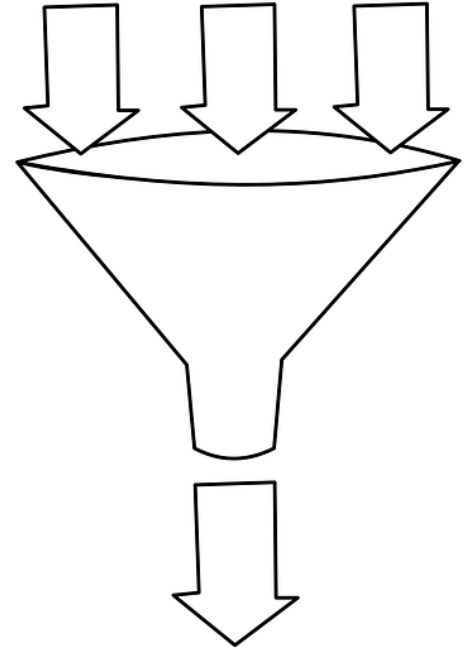
3 aspects

- Type of environment
- Average speed
- Presence of on-board steward



Input

1. Pilots in Europe
2. Appelscha
3. WEpod
4. Rivium ParkShuttle
5. AV vs PT
6. American studies



Pilots in Europe

	Country	Project	Location	Date	Vehicle	Capacity	Speed	Route	Length	Infrastructure	Research	More information
1.	Austria	auto.Bus - Seestadt	Seestadt	June 2019 - end date not mentioned	Navya Arma	Max 11 passengers (11 seated and 0 standing)	Max 20 km/h	Test track leads from the subway station Seestadt via the stops "Seeseiten", "Susanne-Schmida-Gasse", "Schenk-Danzinger-Gasse" and "Maria-Tusch-Straße" to the "FeelGood" Apartments	2000 m	Not mentioned	To follow where the vehicle is currently (as there is no timetable yet): https://www.wienerlinien.at/eportal3/ep/channelView.do?pageTypeId/66533/channelId/-4400687	1. https://www.ait.ac.at/en/news-events/single-view/detail/5318/?no_cache=1 2. https://de.wikipedia.org/wiki/Autonomer_Bus_(Wien)
2.	Austria	Digibus© 2017	Koppl (Salzburg area)	April 2017 - November 2017	Navya Arma	Max 11 passengers (11 seated and 0 standing)	Max 16 km/h	Public road with mixed traffic in a rural area.	1400 m	Road mostly lacking road markings, varying inclines, varying mobile network coverage, varying quality of GNSS and correction signals, other road users driving at speeds up to 60 km/h per hour or varying weather conditions	Salzburg Research Forschungsgesellschaft	1. https://www.digibus.at/en/news/ 2. https://etr.springeropen.com/articles/10.1186/s12544-018-0326-4

118 pilots!

Appelscha – WEpod – Rivium ParkShuttle



Mixed traffic
Little infrastructural
changes
Max 25 km/h
Steward on-board

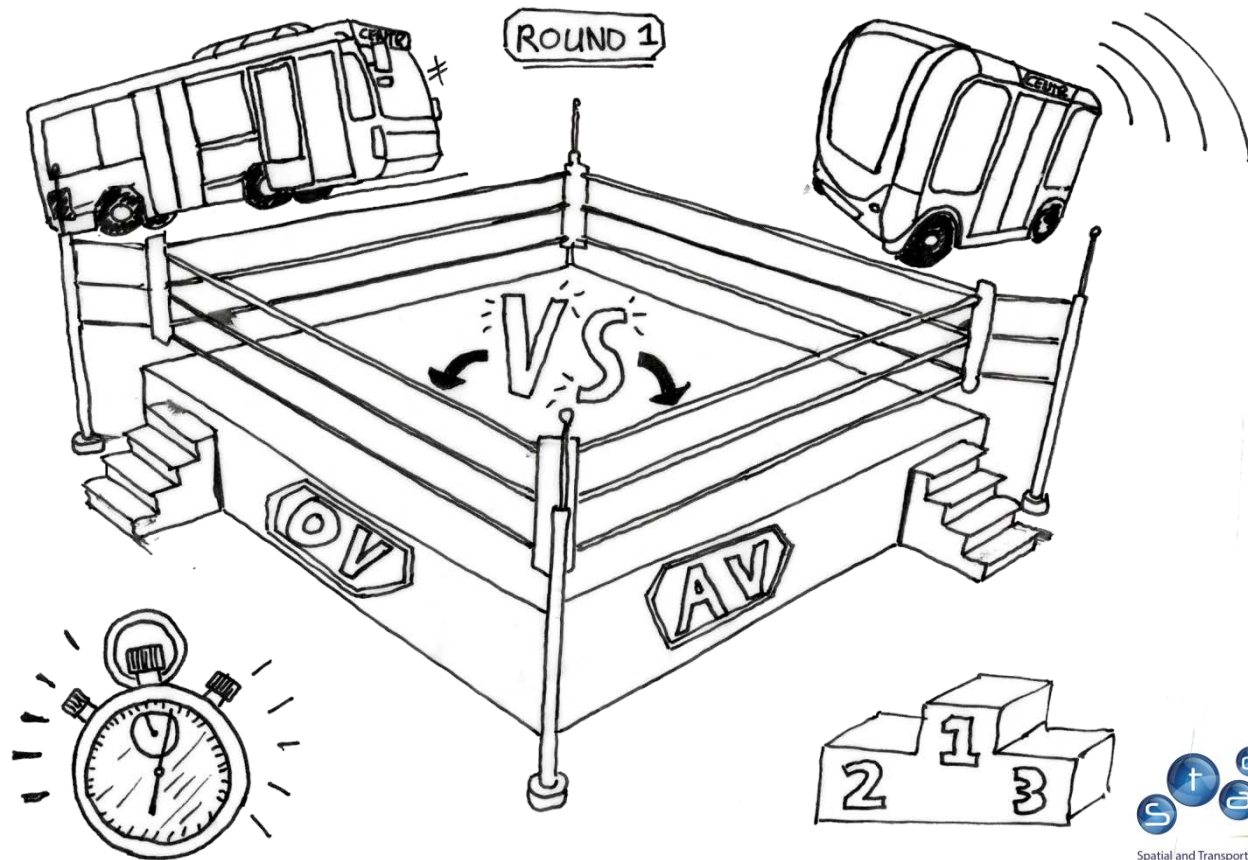


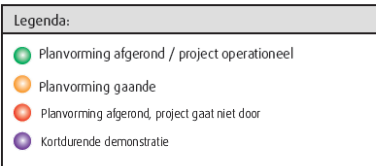
Dedicated
infrastructure
Max 32 km/h
Steward in control
room

Bicycle lane
Little infrastructural
changes
Max 15 km/h
Steward on-board



AV vs PT

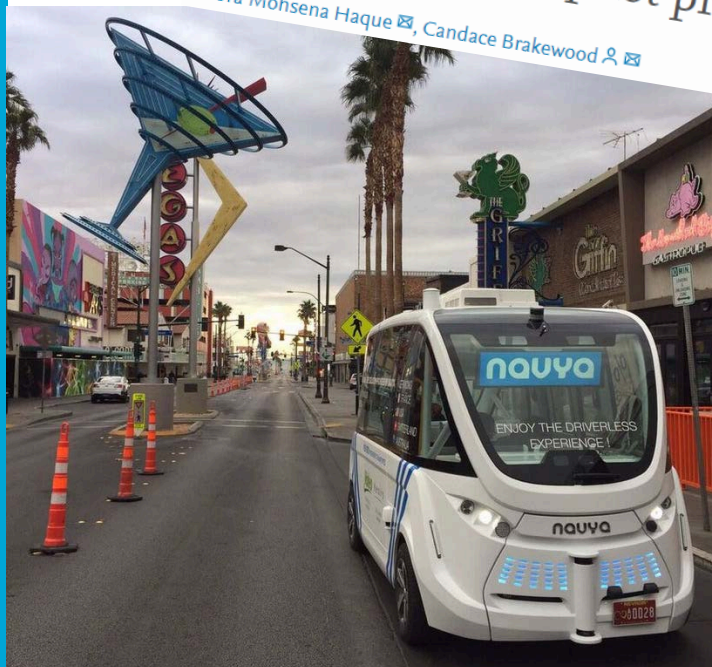




American studies

A synthesis and comparison of American
automated shuttle pilot projects

Antora Mohsena Haque ✉, Candace Brakewood ♀ ✉

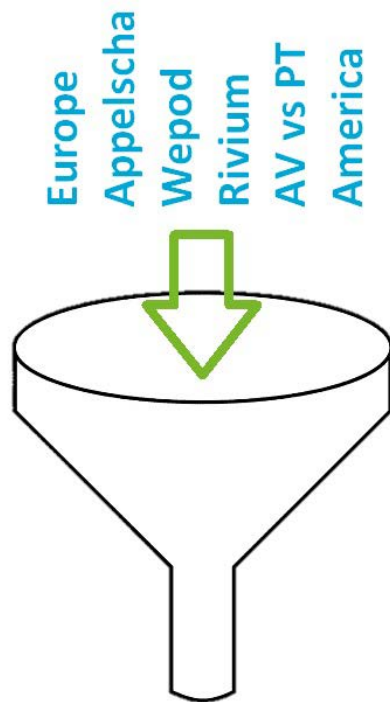


Bloomberg
Philanthropies THE ASPEN INSTITUTE

**We spent 2017 scouring
the globe to understand
how cities are preparing
for AVs**

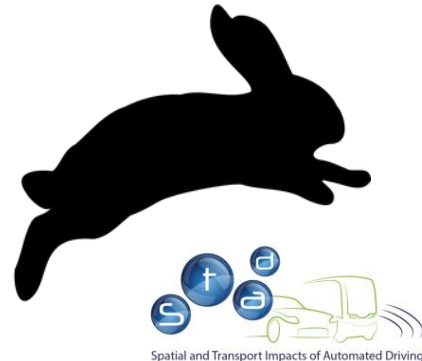
Results

What are the characteristics of promising situations where automated vehicles can be deployed in public transport based on knowledge gained from practice?



How fast do you think the automated shuttles have driven on average?

- A. 15 km/h
- B. 21 km/h
- C. 32 km/h
- D. 40 km/h



Results



Type of environment:

Semi-controlled, publicly accessible



Speed:

Below 21 km/h



Steward:

On-board



Results illustrated



COMPLEXITY

SEPARATED

Made by Arthur Scheltes

MIXED

Conclusion

What are the characteristics of promising situations where automated vehicles can be deployed in public transport based on knowledge gained from practice?

- Semi-controlled, publicly accessible environment
- Low speed (approx. 21 km/h)
- Steward on-board

With the abovementioned requirements, the possible implementations of the vehicles are often limited to short distances, such as first-/last-mile transport.

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Supervisors, co-workers, partners,
everyone who has been involved

Thank you!

I hope we meet again.



<http://stad.tudelft.nl/>