

2020 On-line College Tour Automated Driving Spatial and Transportation Impacts and Meaningful Human Control

Webinar 5 Behaviour











SWOV's mission: "Using our knowledge from scientific research to contribute to safer road traffic."

"Warming up..."

1. Who is interested in owning a self-driving car?

"Warming up..."

- 1. Who is interested in owning a self-driving car?
- 2. Who is interested in owning a self-driving car if the price tag is 20% higher?

"Warming up..."

- 1. Who is interested in owning a self-driving car?
- 2. Who is interested in owning a self-driving car if the price tag is 20% higher?
- 3. Where can we expect the most benefits:
 - A. Environment
 - B. Safety (for driver and other road users)
 - C. Better use of urban space / spatial planning
 - D. Alternative use of time (fo driver)





SWOV's European projects













European Naturalistic Driving Study

Large Scale Naturalistic Driving Observations in Europe

Full dataset UDRIVE is available @ SWOV!





Societal Level Impact of Connected and Automated Vehicles

€ 6,4 million project funded by the European Commission under the Horizon 2020 research framework programme

Project coordinator: Loughborough University

Start date: 1st of December, 2018 – 3 years

Partners: 12, 10 countries





MEDIATOR

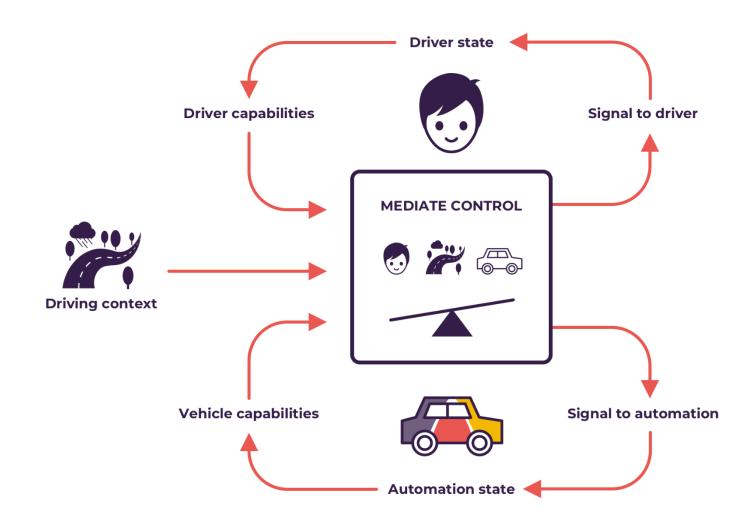
MEDIATING BETWEEN DRIVER AND INTELLIGENT AUTOMATED
TRANSPORT SYSTEMS ON OUR ROADS

COORDINATOR: SWOV, THE NETHERLANDS





Mediator system







News

Research Collaborate -

Publications -

Facts & Figures -

Our mission

Prevent crashes, reduce injuries, save lives!



More about SWOV









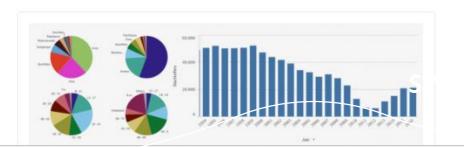
On 28 May experts from Europe and beyond came together in Gothenburg to discuss which societal impacts connected and automated vehicles will have. The workshop was organised within the Horizon 2020...



Measures to stimulate cycling and walking May 8-9, the final conference of the CEDR project ISAAC will take place in Brussels. The result of the project is an

interactive website that allows local, regional and national policy makers to gain...





Today



Microphone and video off



Questions via chat



Presentations

hhtps://stad.tudelft.nl



Recording





Agenda

15.00 – 15.10	Introduction Peter van der Knaap
15.00 – 15.10	introduction Peter van der Knaap
15.10 – 15.30	Reanne Boersma – The road from pilots to implementation. Lessons learned based on knowledge gained from practice
15.30 – 15.50	Daniël Heikoop – The search for personal control over our automated cars: tailor-made or tailor-taught?
15.50 – 16.10	Pablo Nuñez Velasco – Should I stop or should I cross? Interactions between vulnerable road users and automated vehicles
16.00 – 16.30	Questions



Spatial and Transport Impacts of Automated

The road from pilots to implementation. Lessons learned based on knowledge gained from practice

- What can we learn from previous pilots?
- What are promising situations where AVs can be deployed?





The search for personal control over our automated cars: tailor-made or tailor-taught?

- Meaningful human control over automated cars mismatch supply and demand
- Easy tasks taken over, complex tasks left for driver, plus more added
- Individual differences call for individual approaches





Interactions VRUs & Automated Vehicles

- What factors that are important to study?
 - Automation factors
 - Vehicle behaviour factors
 - Psychological factors
- How to study the interactions?
- What can we learn from these experiments?
- What does it mean for future research and for practice?



10-09-2020