"What does vehicle automation with Meaningful Human Control mean in practice?"

Dr. Ir. S.C. Calvert - STAD/MHC College Tour - August 2020





What self-driving cars can't recognize may be a matter of life and death

igineers are racing to program artificial intelligence to recognize different scenarios that numan drivers know innerently



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Stop Saying Driverless Cars Will Help Old People

Study: Autonomous vehicles won't make roads completely safe

The Associated Press Staff Contact Published Thursday, June 4 2020 12/IPM ED

Published Thursday, June 4, 2020 12/IPM EDT Last Updated Thursday, June 4, 2020 3:33PM EDT



MOST-READ



This map shows why it would be 'terrifying' to open Canada-U.S. bord









Leaders Driverless cars are stuck in a jam

DEADLY CRASH WITH SELF-DRIVING UBER



Blame Silicon Valley hype—and the limits of AI

Outline

- Recap on what MHC is
- Application and operationalisation
- Core components
- Application to Truck Platooning
- Quantitative operational test case



Meaningful Human Control



- Philosophy & Ethics
- Behaviour & Psychology
- Traffic & Engineering





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MHC conditions



The system (human operators, operated devices, infrastructures...) should be able to co-vary its behavior with the relevant reasons of the relevant human agent(s) for carrying out X or omitting X

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There is at least one human agent in the system design history or use context who can appreciate the capabilities of the system and her own role as target of potential moral consequences for the system's behaviour



Control: Connecting philosophy & engineering

Expanding a classic theory of control with intuitions from philosophy of action



G. Mecacci & F. Santoni de Sio (2019). "Meaningful human control as reason-responsiveness: the case of dual-mode vehicles". Ethics and Information Technology.

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Poll: How well do you think human ability and morals are considered in current AD-systems?

- A. Very well, almost completely
- B. The main aspects are included
- C. Scarcely, only some aspects are considered
- D. Not at all



Challenges towards application

- Very abstract concept

 (in contrast to physical operational control)
- Complex ethical and behavioural interactions
- Collectively subjective
- Operationalisation allows application in practice



Challenges towards application

- Very abstract concept

 (in contrast to physical operational control)
- Complex ethical and behavioural interactions
- Collectively subjective
- Operationalisation allows application in practice
- 1. (Definition of core components)
- 2. (Simulation modelling framework)
- 3. Conceptual application of MHC
- 4. Quantification of MHC conditions





Case study: Truck platooning



- Lower labour costs?
- Traffic efficiency?

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TP control (physical & practical)

- Operational control of **platoon**:
 - Front driver & (C)ACC-system
 - Human control: Front driver
- Operational control of following trucks:
 - (C)ACC-system
 - Following driver: monitors truck and system
 - Human control: Front driver !?
- Responsibility:
 - Lies with each individual driver (in principle!)
- 'Effective' control is potentially confused or incomplete!





TP control: example

- Situation:
 - TP approaches workzone
 - CACC-system doesn't detect or makes takeover request
 - Front driver is distracted and reacts late
 - Front driver disengages the system by performing an emergency manoeuvre without crashing
 - The following truck drivers cannot react in time and collide with workzone and each other





S. C. Calvert, G. Mecacci, D. D. Heikoop, & F. Santoni de Sio (2018). "Full Platoon Control in Truck Platooning: A Meaningful Human Control Perspective". IEEE ITSC conference, November 4-7, 2018, Maui, USA.

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 - Problem
 - The following drivers are held responsible because they were meant to monitor their own situation of their own trucks





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Applying MHC to examples



- Tracking ('system' compliance to...):
 - Yes, platoon is en-route and compliant
 - Although in an instance, the system cannot perform an emergency manoeuvre, but that is situational rather than by intention.
- Tracing (actor capable to control system...):
 - Front driver: Not met: Performed delayed emergency manoeuvre also puts too great demands on system
 - Following drivers: Not met: unrealistic transition of control demand
 - ADS designer: No MHC, outside ODD (hence TO-request made)



 Both system design and driver performance translate to a lack of MHC (even before an accident) for the case

TP control and challenges

- Operational control and responsibility not aligned
- Misbalance in:

TP control and challenges

- Operational control and responsibility not aligned
- Misbalance in:
 - Operational control vs 'effective human' control
 - Behavioural capabilities of drivers (cognitive)
 - Ethical issues (demands, accountability and responsibility)









with Meaningful Human Control". Forthcoming

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S. C. Calvert, & G. Mecacci (2020). "A mathematical system control description of Cooperative and Automated Driving in mixed urban traffic with Meaningful Human Control". Forthcoming



Reaction to 'reasons' of:

- Duration (strategic)
- Safety (tactical)





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Why is operationalisation important?

- Makes abstract concept applicable in practice
- Demonstrates ways that MHC can be considered in vehicle and infrastructure design
- Demonstrates an approach to evaluate the extent of MHC
- Demonstrates potential policy influence on MHC



Question: Where do you see potential applications of MHC in your work practice or domain?

Get involved!

Not the end of the story

- Proper AV-systems require ethical and behavioural considerations!
- How does your AV-system consider this?
- Are you willing to investigate options to optimise you're AV-system
- We now have the building blocks, so let's build!



Questions

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